

$$\mathbf{u} = \mathbf{N}\mathbf{d} \quad \boldsymbol{\varepsilon} = \mathbf{B}\mathbf{d} \quad \boldsymbol{\sigma} = \mathbf{D}\boldsymbol{\varepsilon} = \mathbf{D}\mathbf{B}\mathbf{d} = \mathbf{S}\mathbf{d}$$

$$\mathbf{Q} = \int_{S_q} \mathbf{N}_s^T \mathbf{q}_b dS + \int_V \mathbf{N}^T \mathbf{q} dV + \int_V \mathbf{B}^T \mathbf{D} \boldsymbol{\varepsilon}_0 dV - \int_V \mathbf{B}^T \boldsymbol{\sigma}_0 dV$$

$$\mathbf{d}_a^* = \mathbf{K}_{aa}^{*-1} \mathbf{S}_a^* - \mathbf{K}_{aa}^{*-1} \mathbf{K}_{ap}^* \mathbf{d}_p^*$$

$$\mathbf{R}_p^* = \mathbf{S}_p^* - \mathbf{Q}_p^* = \mathbf{K}_{pa}^* \mathbf{d}_a^* + \mathbf{K}_{pp}^* \mathbf{d}_p^* - \mathbf{Q}_p^*$$

LINIJSKI KONAČNI ELEMENTI

Aksijalno naprezanje



$$N_1 = 1 - \frac{x}{L} \quad N_2 = \frac{x}{L}$$

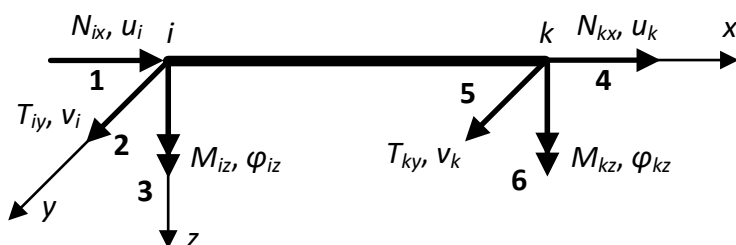
$$\mathbf{B} = \begin{bmatrix} -\frac{1}{L} & \frac{1}{L} \end{bmatrix} \quad \mathbf{D} = [EA]$$

$$\mathbf{k} = \frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\mathbf{T} = \begin{bmatrix} \cos \alpha & \sin \alpha & 0 & 0 \\ 0 & 0 & \cos \alpha & \sin \alpha \end{bmatrix}$$

$$\mathbf{k}^* = \frac{EA}{L} \begin{bmatrix} \cos^2 \alpha & \cos \alpha \sin \alpha & -\cos^2 \alpha & -\cos \alpha \sin \alpha \\ \cos \alpha \sin \alpha & \sin^2 \alpha & -\cos \alpha \sin \alpha & -\sin^2 \alpha \\ -\cos^2 \alpha & -\cos \alpha \sin \alpha & \cos^2 \alpha & \cos \alpha \sin \alpha \\ -\cos \alpha \sin \alpha & -\sin^2 \alpha & \cos \alpha \sin \alpha & \sin^2 \alpha \end{bmatrix}$$

Aksijalno naprezanje i savijanje u x – y ravni



$$N_2 = 1 - \frac{3x^2}{L^2} + \frac{2x^3}{L^3}$$

$$N_3(x) = x - \frac{2x^2}{L} + \frac{x^3}{L^2}$$

$$N_5 = \frac{3x^2}{L^2} - \frac{2x^3}{L^3}$$

$$N_6 = -\frac{x^2}{L} + \frac{x^3}{L^2}$$

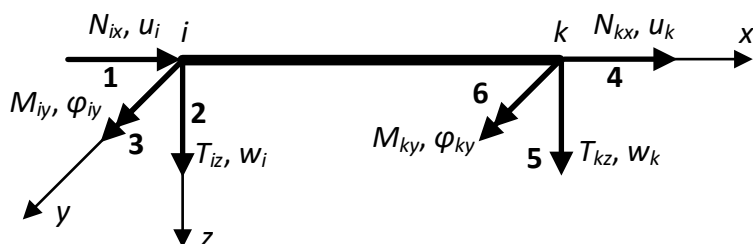
$$\mathbf{B}_{xy} = \begin{bmatrix} -\frac{6}{L^2} + \frac{12x}{L^3} & -\frac{4}{L} + \frac{6x}{L^2} & \frac{6}{L^2} - \frac{12x}{L^3} & -\frac{2}{L} + \frac{6x}{L^2} \end{bmatrix}$$

$$\mathbf{D}_{xy} = [EI_z]$$

$$\mathbf{k}_{xy} = \begin{bmatrix} \frac{EA}{L} & 0 & 0 & -\frac{EA}{L} & 0 & 0 \\ 0 & \frac{12EI_z}{L^3} & \frac{6EI_z}{L^2} & 0 & -\frac{12EI_z}{L^3} & \frac{6EI_z}{L^2} \\ 0 & \frac{6EI_z}{L^2} & \frac{4EI_z}{L} & 0 & -\frac{6EI_z}{L^2} & \frac{2EI_z}{L} \\ -\frac{EA}{L} & 0 & 0 & \frac{EA}{L} & 0 & 0 \\ 0 & -\frac{12EI_z}{L^3} & -\frac{6EI_z}{L^2} & 0 & \frac{12EI_z}{L^3} & -\frac{6EI_z}{L^2} \\ 0 & \frac{6EI_z}{L^2} & \frac{2EI_z}{L} & 0 & -\frac{6EI_z}{L^2} & \frac{4EI_z}{L} \end{bmatrix}$$

$$T_y = -EI_z \frac{6(2v_1 - 2v_2 + L(\varphi_{1z} + \varphi_{2z}))}{L^3}$$

Aksijalno naprezanje i savijanje u x – z ravni



$$N_2 = 1 - \frac{3x^2}{L^2} + \frac{2x^3}{L^3}$$

$$N_3 = -x + \frac{2x^2}{L} - \frac{x^3}{L^2}$$

$$N_5 = \frac{3x^2}{L^2} - \frac{2x^3}{L^3}$$

$$N_6 = \frac{x^2}{L} - \frac{x^3}{L^2}$$

$$\mathbf{B}_{xz} = \begin{bmatrix} \frac{6}{L^2} - \frac{12x}{L^3} & -\frac{4}{L} + \frac{6x}{L^2} & -\frac{6}{L^2} + \frac{12x}{L^3} & -\frac{2}{L} + \frac{6x}{L^2} \end{bmatrix}$$

$$\mathbf{D}_{xz} = [EI_y]$$

$$\mathbf{k}_{xz} = \begin{bmatrix} \frac{EA}{L} & 0 & 0 & -\frac{EA}{L} & 0 & 0 \\ 0 & \frac{12EI_y}{L^3} & -\frac{6EI_y}{L^2} & 0 & -\frac{12EI_y}{L^3} & \frac{6EI_y}{L^2} \\ 0 & -\frac{6EI_y}{L^2} & \frac{4EI_y}{L} & 0 & \frac{6EI_y}{L^2} & -\frac{2EI_y}{L} \\ -\frac{EA}{L} & 0 & 0 & \frac{EA}{L} & 0 & 0 \\ 0 & -\frac{12EI_y}{L^3} & \frac{6EI_y}{L^2} & 0 & \frac{12EI_y}{L^3} & -\frac{6EI_y}{L^2} \\ 0 & \frac{6EI_y}{L^2} & -\frac{2EI_y}{L} & 0 & -\frac{6EI_y}{L^2} & \frac{4EI_y}{L} \end{bmatrix}$$

$$T_z = EI_y \frac{6(-2w_1 + 2w_2 + L(\varphi_{1y} + \varphi_{2y}))}{L^3}$$

Matrica transformacije

$$\mathbf{T} = \begin{bmatrix} \cos \alpha & \sin \alpha & 0 & 0 & 0 & 0 \\ -\sin \alpha & \cos \alpha & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & \cos \alpha & \sin \alpha & 0 \\ 0 & 0 & 0 & -\sin \alpha & \cos \alpha & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Transformacija

$$\mathbf{k}^* = \mathbf{T}^T \mathbf{k} \mathbf{T}$$

$$\mathbf{d} = \mathbf{T} \mathbf{d}^*$$

$$\mathbf{Q} = \mathbf{T} \mathbf{Q}^*$$

$$\mathbf{R} = \mathbf{T} \mathbf{R}^*$$

$$\mathbf{d}^* = \mathbf{T}^T \mathbf{d}$$

$$\mathbf{Q}^* = \mathbf{T}^T \mathbf{Q}$$

$$\mathbf{R}^* = \mathbf{T}^T \mathbf{R}$$

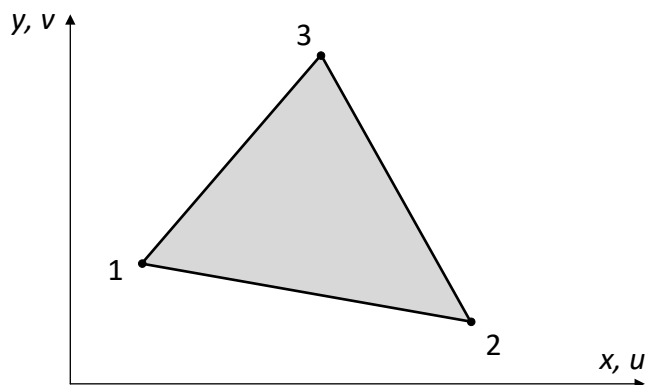
RAVANSKO STANJE NAPONA

$$\mathbf{D} = \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix}$$

RAVANSKO STANJE DEFORMACIJE

$$\mathbf{D} = \frac{E}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1-\nu & \nu & 0 \\ \nu & 1-\nu & 0 \\ 0 & 0 & \frac{1-2\nu}{2} \end{bmatrix}$$

TROUGAONI KONAČNI ELEMENT (CST KE). Linearna interpolacija



$$a_1 = x_2 y_3 - x_3 y_2, \quad a_2 = x_3 y_1 - x_1 y_3, \quad a_3 = x_1 y_2 - x_2 y_1$$

$$b_1 = y_2 - y_3, \quad b_2 = y_3 - y_1, \quad b_3 = y_1 - y_2$$

$$c_1 = x_3 - x_2, \quad c_2 = x_1 - x_3, \quad c_3 = x_2 - x_1$$

$$A = \frac{1}{2}(a_1 + a_2 + a_3)$$

$$N_i = \frac{1}{2A}(a_i + b_i x + c_i y), \quad i = 1, 2, 3$$

$$\mathbf{B} = \frac{1}{2A} \begin{bmatrix} b_1 & 0 & b_2 & 0 & b_3 & 0 \\ 0 & c_1 & 0 & c_2 & 0 & c_3 \\ c_1 & b_1 & c_2 & b_2 & c_3 & b_3 \end{bmatrix}$$

$$\mathbf{k} = \frac{h}{4A} \begin{bmatrix} b_1 & 0 & c_1 \\ 0 & c_1 & b_1 \\ b_2 & 0 & c_2 \\ 0 & c_2 & b_2 \\ b_3 & 0 & c_3 \\ 0 & c_3 & b_3 \end{bmatrix} \mathbf{D} \begin{bmatrix} b_1 & 0 & b_2 & 0 & b_3 & 0 \\ 0 & c_1 & 0 & c_2 & 0 & c_3 \\ c_1 & b_1 & c_2 & b_2 & c_3 & b_3 \end{bmatrix}$$

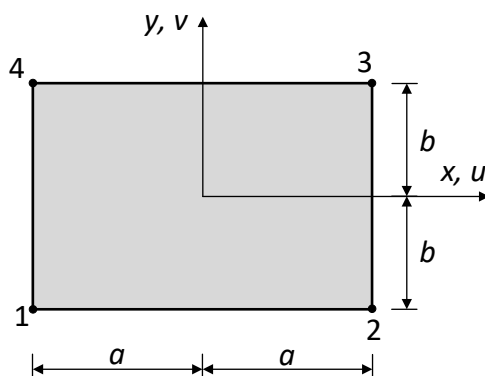
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$$\mathbf{k} = \frac{h}{4A} \begin{pmatrix} b_1^2 D_{11} + c_1^2 D_{33} & b_1 c_1 (D_{12} + D_{33}) & b_1 b_2 D_{11} + c_1 c_2 D_{33} \\ b_1 c_1 (D_{21} + D_{33}) & c_1^2 D_{22} + b_1^2 D_{33} & b_2 c_1 D_{21} + b_1 c_2 D_{33} \\ b_1 b_2 D_{11} + c_1 c_2 D_{33} & b_2 c_1 D_{12} + b_1 c_2 D_{33} & b_2^2 D_{11} + c_2^2 D_{33} \\ b_1 c_2 D_{21} + b_2 c_1 D_{33} & c_1 c_2 D_{22} + b_1 b_2 D_{33} & b_2 c_2 (D_{21} + D_{33}) \\ b_1 b_3 D_{11} + c_1 c_3 D_{33} & b_3 c_1 D_{12} + b_1 c_3 D_{33} & b_2 b_3 D_{11} + c_2 c_3 D_{33} \\ b_1 c_3 D_{21} + b_3 c_1 D_{33} & c_1 c_3 D_{22} + b_1 b_3 D_{33} & b_2 c_3 D_{21} + b_3 c_2 D_{33} \end{pmatrix} \dots$$

$$\dots \begin{pmatrix} b_1 c_2 D_{12} + b_2 c_1 D_{33} & b_1 b_3 D_{11} + c_1 c_3 D_{33} & b_1 c_3 D_{12} + b_3 c_1 D_{33} \\ c_1 c_2 D_{22} + b_1 b_2 D_{33} & b_3 c_1 D_{21} + b_1 c_3 D_{33} & c_1 c_3 D_{22} + b_1 b_3 D_{33} \\ b_2 c_2 (D_{12} + D_{33}) & b_2 b_3 D_{11} + c_2 c_3 D_{33} & b_2 c_3 D_{12} + b_3 c_2 D_{33} \\ c_2^2 D_{22} + b_2^2 D_{33} & b_3 c_2 D_{21} + b_2 c_3 D_{33} & c_2 c_3 D_{22} + b_2 b_3 D_{33} \\ b_3 c_2 D_{12} + b_2 c_3 D_{33} & b_3^2 D_{11} + c_3^2 D_{33} & b_3 c_3 (D_{12} + D_{33}) \\ \dots & c_2 c_3 D_{22} + b_2 b_3 D_{33} & b_3 c_3 (D_{21} + D_{33}) & c_3^2 D_{22} + b_3^2 D_{33} \end{pmatrix}$$

$$\mathbf{S} = \frac{1}{2A} \begin{pmatrix} b_1 D_{11} & c_1 D_{12} & b_2 D_{11} & c_2 D_{12} & b_3 D_{11} & c_3 D_{12} \\ b_1 D_{21} & c_1 D_{22} & b_2 D_{21} & c_2 D_{22} & b_3 D_{21} & c_3 D_{22} \\ c_1 D_{33} & b_1 D_{33} & c_2 D_{33} & b_2 D_{33} & c_3 D_{33} & b_3 D_{33} \end{pmatrix}$$

PRAVOUGAONI KONAČNI ELEMENT. Bilinearna interpolacija



$$N_1 = \frac{1}{4} \left(1 - \frac{x}{a} \right) \left(1 - \frac{y}{b} \right) \quad N_2 = \frac{1}{4} \left(1 + \frac{x}{a} \right) \left(1 - \frac{y}{b} \right)$$

$$N_3 = \frac{1}{4} \left(1 + \frac{x}{a} \right) \left(1 + \frac{y}{b} \right) \quad N_4 = \frac{1}{4} \left(1 - \frac{x}{a} \right) \left(1 + \frac{y}{b} \right)$$

$$\mathbf{B} = \frac{1}{4ab} \begin{bmatrix} -b+y & 0 & b-y & 0 & b+y & 0 & -b-y & 0 \\ 0 & -a+x & 0 & -a-x & 0 & a+x & 0 & a-x \\ -a+x & -b+y & -a-x & b-y & a+x & b+y & a-x & -b-y \end{bmatrix}$$

$$\mathbf{k} = \frac{h}{12ab} \begin{pmatrix} 4(b^2 D_{11} + a^2 D_{33}) & 3ab(D_{12} + D_{33}) & -4b^2 D_{11} + 2a^2 D_{33} & 3ab(D_{12} - D_{33}) \\ 3ab(D_{21} + D_{33}) & 4(a^2 D_{22} + b^2 D_{33}) & 3ab(-D_{21} + D_{33}) & 2a^2 D_{22} - 4b^2 D_{33} \\ -4b^2 D_{11} + 2a^2 D_{33} & 3ab(-D_{12} + D_{33}) & 4(b^2 D_{11} + a^2 D_{33}) & -3ab(D_{12} + D_{33}) \\ 3ab(D_{21} - D_{33}) & 2a^2 D_{22} - 4b^2 D_{33} & -3ab(D_{21} + D_{33}) & 4(a^2 D_{22} + b^2 D_{33}) \\ -2(b^2 D_{11} + a^2 D_{33}) & -3ab(D_{12} + D_{33}) & 2b^2 D_{11} - 4a^2 D_{33} & 3ab(-D_{12} + D_{33}) \\ -3ab(D_{21} + D_{33}) & -2(a^2 D_{22} + b^2 D_{33}) & 3ab(D_{21} - D_{33}) & -4a^2 D_{22} + 2b^2 D_{33} \\ 2b^2 D_{11} - 4a^2 D_{33} & 3ab(D_{12} - D_{33}) & -2(b^2 D_{11} + a^2 D_{33}) & 3ab(D_{12} + D_{33}) \\ 3ab(-D_{21} + D_{33}) & -4a^2 D_{22} + 2b^2 D_{33} & 3ab(D_{21} + D_{33}) & -2(a^2 D_{22} + b^2 D_{33}) \dots \\ -2(b^2 D_{11} + a^2 D_{33}) & -3ab(D_{12} + D_{33}) & 2b^2 D_{11} - 4a^2 D_{33} & 3ab(-D_{12} + D_{33}) \\ -3ab(D_{21} + D_{33}) & -2(a^2 D_{22} + b^2 D_{33}) & 3ab(D_{21} - D_{33}) & -4a^2 D_{22} + 2b^2 D_{33} \\ 2b^2 D_{11} - 4a^2 D_{33} & 3ab(D_{12} - D_{33}) & -2(b^2 D_{11} + a^2 D_{33}) & 3ab(D_{12} + D_{33}) \\ 3ab(-D_{21} + D_{33}) & -4a^2 D_{22} + 2b^2 D_{33} & 3ab(D_{21} + D_{33}) & -2(a^2 D_{22} + b^2 D_{33}) \\ 4(b^2 D_{11} + a^2 D_{33}) & 3ab(D_{12} + D_{33}) & -4b^2 D_{11} + 2a^2 D_{33} & 3ab(D_{12} - D_{33}) \\ 3ab(D_{21} + D_{33}) & 4(a^2 D_{22} + b^2 D_{33}) & 3ab(-D_{21} + D_{33}) & 2a^2 D_{22} - 4b^2 D_{33} \\ -4b^2 D_{11} + 2a^2 D_{33} & 3ab(-D_{12} + D_{33}) & 4(b^2 D_{11} + a^2 D_{33}) & -3ab(D_{12} + D_{33}) \\ 3ab(D_{21} - D_{33}) & 2a^2 D_{22} - 4b^2 D_{33} & -3ab(D_{21} + D_{33}) & 4(a^2 D_{22} + b^2 D_{33}) \dots \end{pmatrix}$$

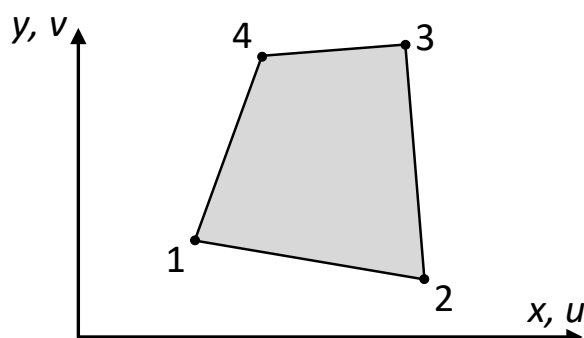
$$S = \frac{1}{4ab} \begin{pmatrix} D11 (-b+y) & D12 (-a+x) & D11 (b-y) & -D12 (a+x) \\ D21 (-b+y) & D22 (-a+x) & D21 (b-y) & -D22 (a+x) \\ D33 (-a+x) & D33 (-b+y) & -D33 (a+x) & D33 (b-y) \end{pmatrix} \dots$$

$$\dots \begin{pmatrix} D11 (b+y) & D12 (a+x) & -D11 (b+y) & D12 (a-x) \\ D21 (b+y) & D22 (a+x) & -D21 (b+y) & D22 (a-x) \\ D33 (a+x) & D33 (b+y) & D33 (a-x) & -D33 (b+y) \end{pmatrix}$$

$$T = \begin{bmatrix} T_1 & & & \\ & T_2 & & \\ & & T_3 & \\ & & & T_4 \end{bmatrix}$$

$$T_i = \begin{bmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{bmatrix}, \quad i = 1, 2, 3, 4$$

IZOPARAMETARSKI KONAČNI ELEMENT SA 4. ČVORA



$$N_i(\xi, \eta) = \frac{1}{4}(1 + \xi_i \xi)(1 + \eta_i \eta), \quad i = 1, 2, 3, 4$$

$$B = \begin{bmatrix} \frac{\partial N_1}{\partial x} & 0 & \frac{\partial N_2}{\partial x} & 0 & \frac{\partial N_3}{\partial x} & 0 & \frac{\partial N_4}{\partial x} & 0 \\ 0 & \frac{\partial N_1}{\partial y} & 0 & \frac{\partial N_2}{\partial y} & 0 & \frac{\partial N_3}{\partial y} & 0 & \frac{\partial N_4}{\partial y} \\ \frac{\partial N_1}{\partial y} & \frac{\partial N_1}{\partial x} & \frac{\partial N_2}{\partial y} & \frac{\partial N_2}{\partial x} & \frac{\partial N_3}{\partial y} & \frac{\partial N_3}{\partial x} & \frac{\partial N_4}{\partial y} & \frac{\partial N_4}{\partial x} \end{bmatrix}$$

$$k = \int_{-1}^1 \int_{-1}^1 B^T D B h \det J d\xi d\eta \quad Q = \int_{-1}^1 \int_{-1}^1 N^T q h \det J d\xi d\eta$$

$$J = \begin{bmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial y}{\partial \xi} \\ \frac{\partial x}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^4 \frac{\partial N_i}{\partial \xi} x_i & \sum_{i=1}^4 \frac{\partial N_i}{\partial \xi} y_i \\ \sum_{i=1}^4 \frac{\partial N_i}{\partial \eta} x_i & \sum_{i=1}^4 \frac{\partial N_i}{\partial \eta} y_i \end{bmatrix} = \begin{bmatrix} J_{11} & J_{12} \\ J_{21} & J_{22} \end{bmatrix}$$

$$\begin{aligned}\frac{\partial N_1}{\partial \xi} &= \frac{1}{4}(-1+\eta) & \frac{\partial N_2}{\partial \xi} &= \frac{1}{4}(1-\eta) & \frac{\partial N_3}{\partial \xi} &= \frac{1}{4}(1+\eta) & \frac{\partial N_4}{\partial \xi} &= \frac{1}{4}(-1-\eta) \\ \frac{\partial N_1}{\partial \eta} &= \frac{1}{4}(-1+\xi) & \frac{\partial N_2}{\partial \eta} &= \frac{1}{4}(-1-\xi) & \frac{\partial N_3}{\partial \eta} &= \frac{1}{4}(1+\xi) & \frac{\partial N_4}{\partial \eta} &= \frac{1}{4}(1-\xi)\end{aligned}$$

$$J_{11} = \frac{\partial x}{\partial \xi} = \sum_{i=1}^4 \frac{\partial N_i}{\partial \xi} x_i = \frac{1}{4} [x_1(-1+\eta) + x_2(1-\eta) + x_3(1+\eta) + x_4(-1-\eta)]$$

$$J_{12} = \frac{\partial y}{\partial \xi} = \sum_{i=1}^4 \frac{\partial N_i}{\partial \xi} y_i = \frac{1}{4} [y_1(-1+\eta) + y_2(1-\eta) + y_3(1+\eta) + y_4(-1-\eta)]$$

$$J_{21} = \frac{\partial x}{\partial \eta} = \sum_{i=1}^4 \frac{\partial N_i}{\partial \eta} x_i = \frac{1}{4} [x_1(-1+\xi) + x_2(-1-\xi) + x_3(1+\xi) + x_4(1-\xi)]$$

$$J_{22} = \frac{\partial y}{\partial \eta} = \sum_{i=1}^4 \frac{\partial N_i}{\partial \eta} y_i = \frac{1}{4} [y_1(-1+\xi) + y_2(-1-\xi) + y_3(1+\xi) + y_4(1-\xi)]$$

$$\mathbf{J}^{-1} = \frac{1}{\det \mathbf{J}} \begin{bmatrix} \sum_{i=1}^4 \frac{\partial N_i}{\partial \eta} y_i & -\sum_{i=1}^4 \frac{\partial N_i}{\partial \xi} y_i \\ -\sum_{i=1}^4 \frac{\partial N_i}{\partial \eta} x_i & \sum_{i=1}^4 \frac{\partial N_i}{\partial \xi} x_i \end{bmatrix} = \frac{1}{\det \mathbf{J}} \begin{bmatrix} J_{22} & -J_{12} \\ -J_{21} & J_{11} \end{bmatrix}$$

$$\det \mathbf{J} = J_{11}J_{22} - J_{12}J_{21}$$

$$\begin{cases} \frac{\partial N_i}{\partial x} \\ \frac{\partial N_i}{\partial y} \end{cases} = \mathbf{J}^{-1} \begin{cases} \frac{\partial N_i}{\partial \xi} \\ \frac{\partial N_i}{\partial \eta} \end{cases} \Rightarrow \begin{aligned} \frac{\partial N_i}{\partial x} &= \frac{1}{\det \mathbf{J}} \left(J_{22} \frac{\partial N_i}{\partial \xi} - J_{12} \frac{\partial N_i}{\partial \eta} \right) \\ \frac{\partial N_i}{\partial y} &= \frac{1}{\det \mathbf{J}} \left(-J_{21} \frac{\partial N_i}{\partial \xi} + J_{11} \frac{\partial N_i}{\partial \eta} \right) \end{aligned}$$

$$\frac{\partial N_1}{\partial x} = \frac{1}{8 \det \mathbf{J}} [y_2(1-\eta) + y_3(-\xi+\eta) + y_4(-1+\xi)] \quad \frac{\partial N_1}{\partial y} = \frac{1}{8 \det \mathbf{J}} [x_2(-1+\eta) + x_3(\xi-\eta) + x_4(1-\xi)]$$

$$\frac{\partial N_2}{\partial x} = \frac{1}{8 \det \mathbf{J}} [y_1(-1+\eta) + y_3(1+\xi) + y_4(-\xi-\eta)] \quad \frac{\partial N_2}{\partial y} = \frac{1}{8 \det \mathbf{J}} [x_1(1-\eta) + x_3(-1-\xi) + x_4(\xi+\eta)]$$

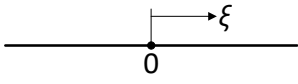
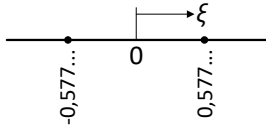
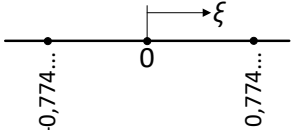
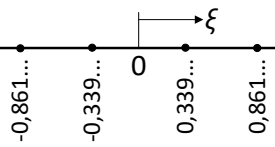
$$\frac{\partial N_3}{\partial x} = \frac{1}{8 \det \mathbf{J}} [y_1(\xi-\eta) + y_2(-1-\xi) + y_4(1+\eta)] \quad \frac{\partial N_3}{\partial y} = \frac{1}{8 \det \mathbf{J}} [x_1(-\xi+\eta) + x_2(1+\xi) + x_4(-1-\eta)]$$

$$\frac{\partial N_4}{\partial x} = \frac{1}{8 \det \mathbf{J}} [y_1(1-\xi) + y_2(\xi+\eta) + y_3(-1-\eta)] \quad \frac{\partial N_4}{\partial y} = \frac{1}{8 \det \mathbf{J}} [x_1(-1+\xi) + x_2(-\xi-\eta) + x_3(1+\eta)]$$

NUMERIČKA INTEGRACIJA

$$\int_{-1}^1 \int_{-1}^1 F(\xi, \eta) d\xi d\eta = \sum_{j=1}^{n_j} w_j \left(\sum_{i=1}^{n_i} w_i F(\xi_i, \eta_j) \right) = \sum_{i=1}^{n_i} \sum_{j=1}^{n_j} w_{ij} F(\xi_i, \eta_j), \quad w_{ij} = w_i w_j$$

Tačke integracije i težinski koeficijenti

n	Stepen polinoma	i	ξ_i	w_i	
1	1	1	0,0	2,0	
2	3	1 2	$-1/\sqrt{3}$ $1/\sqrt{3}$	1,0 1,0	
3	5	1 2 3	$-\sqrt{3/5}$ 0 $\sqrt{3/5}$	5/9 8/9 5/9	
4	7	1 2 3 4	$-0,8611363116$ $-0,3399810436$ $0,3399810436$ $0,8611363116$	0,3478548451 0,6521451549 0,6521451549 0,3478548451	
5	9	1 2 3 4 5	$-0,9061798459$ $-0,5384693101$ 0 $0,5384693101$ $0,9061798459$	0,2369268851 0,4786286705 0,5688888889 0,4786286705 0,2369268851	